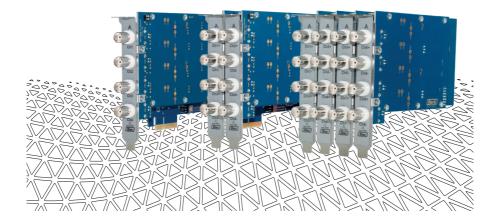


# Data Acquisition Cards





User Manual

TPCE TPCE-LE

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# Personal safety when installing in your computer

High voltages may be present inside computer equipment. Before installing any of the hardware in this package, or removing the protective covers of any computer equipment, turn off power switches and disconnect power cords. Do not reconnect the power cords until the hardware is installed and the system cover is closed.

#### Attention

The boards must not be installed into industrial PC's, which do not keep the necessary EMC standards.

#### ESD (Electrostatic Discharge) precautions

To avoid damaging computer components and accessories when installing or removing an Elsys Instruments Data Acquisition module, follow standard electrostatic discharge (ESD) precautions:

- When your computer case is open and its internal parts are exposed, do not touch any internal parts unnecessarily.
- Always wear a grounded strap or work on an ESD-protective mat.
- Do not remove the Data Acquisition module from its protective bag until you are properly grounded.
- Handle the Data Acquisition module by its edges or by the metal bracket.
- Do not touch any pin, contact, lead or component on the Data Acquisition module.

#### Content

1. Introduction 4
1.1 Quick Installation
1.2 System Requirements
1.3 Multi-Board Systems
1.4 Operation Modes
1.5 TPCE & TPCE-LE Block Diagram7
1.6 Standard Filter
1.7 Trigger Logic
1.8 Anti-Aliasing Filter Module9
2. Input and Outputs 10
2.1 Analog Inputs10
2.2 Digital In/Out and Markers12
3. Specification14
3.1 Power Consumption14
3.1 Power Consumption143.2 Operating Conditions14
3.1 Power Consumption14
3.1 Power Consumption143.2 Operating Conditions14
3.1 Power Consumption143.2 Operating Conditions143.3 Mechanical Specification14
3.1 Power Consumption143.2 Operating Conditions143.3 Mechanical Specification143.4 TPCE Specification153.5 TPCE-LE Specification17
3.1 Power Consumption143.2 Operating Conditions143.3 Mechanical Specification143.4 TPCE Specification153.5 TPCE-LE Specification174. Synchronization19
3.1 Power Consumption       14         3.2 Operating Conditions       14         3.3 Mechanical Specification       14         3.4 TPCE Specification       15         3.5 TPCE-LE Specification       17         4. Synchronization       19         4.1 StarHub       19
3.1 Power Consumption143.2 Operating Conditions143.3 Mechanical Specification143.4 TPCE Specification153.5 TPCE-LE Specification174. Synchronization19
3.1 Power Consumption143.2 Operating Conditions143.3 Mechanical Specification143.4 TPCE Specification153.5 TPCE-LE Specification174. Synchronization194.1 StarHub194.2 SyncLink19
3.1 Power Consumption       14         3.2 Operating Conditions       14         3.3 Mechanical Specification       14         3.4 TPCE Specification       15         3.5 TPCE-LE Specification       17         4. Synchronization       19         4.1 StarHub       19

## 1. Introduction

#### 1.1 Quick Installation

- Before installing the TPCE module into the computer, the correct channel group must be set with the small rotary switch. See Chapter "Board Number Configuration".
- If sufficient free PCIe card slots are available, single places can remain empty between the modules. Thus the heat dissipation improves. Besides the BNC plugs are better accessible.
- If more than one board is installed, a StarHub synchronization board must be connected to all installed boards.
- For precise measurements, good ground contact between the boards and the chassis is needed.
- Close the computer and turn it on
- Install the TpcServer Setup which installs
   all device drivers and services needed for
   proper operation.

#### 1.2 System Requirements

The TPCE cards require the following minimal computer configuration:

- Industrial PC or compatible
- CPU Intel i5 or better
- 17 inch Full HD Screen with a resolution of 1920x1080 or higher
- RAM minimum 2 GB, recommended 4 GB
- TPCE: One x4 PCIe slot each per 4-channel board
- TPCE-LE: One x1 PCIe slot each per 4-channel board
- 8-channel boards need two slots. With differential modules the number of required slots has to be doubled.
- Windows 10 or 11, 64 Bit
- Power supply inside of the PC with enough power.

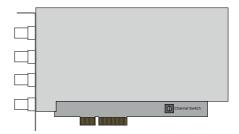
#### 1.3 Multi-Board Systems

Large data acquisition systems can be set up based on all Elsys DAQ cards. Depending on the host system, instruments with up to 64 channels can be realized in one device. Larger or distributed systems can be set up by synchronizing several devices with each other.

#### **Board Number Configuration**

If more than one card is installed in a device, each card must be configured with a different card letter. This can be done by configuring the channel switch on the measuring card.

Switch Position	Board Letter	Channels
0	А	A1 - A4 / A1 - A8
1	В	B1 - B4 / B1 - B8
2	С	C1 - C4 / C1 - C8
F	Р	P1 - P4 / P1 - P8



#### 1.4 Operation Modes

There are four different operation modes in which the data acquisition cards can be used. Any of these operation modes are ready to use in all driver interfaces or Application software.

#### Scope

In Scope mode, the board runs like an Oscilloscope. Incoming data from the ADC are written into the on-board memory until a trigger condition occurs. After the trigger condition, the measurement continuous until the post-trigger time is over and stops. The length of the measurement is limited by the maximum memory available on the board.

#### Multi-Block

Multi-Block Mode works like the Scope mode but with the addition that the available onboard memory is split up in several blocks. On each trigger, a new part of the memory is used. This way, the on-board memory can be used more effective than in the Scope mode. The maximum number of blocks is limited by the block size and the available memory.

#### Continuous

In the Continuous mode incoming data from the ADC's are buffered on the on-board memory an then transfered immediately to the hard disk. The maximum recording length is only limited by the hard disk size. The amount of data produced per second depend on the used sampling rate and the number of activated channels. If the data rate is higher than the PCIe interface or the hard-disk write throughput, some data from the on-board buffer get lost.

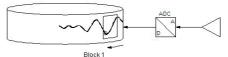
### ECR Event Controlled Recording

(This mode is optional)

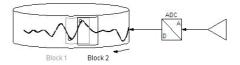
The ECR mode allows targeted acquisition of cyclic or sporadically arising events. This implies that the registration of measuring data only occurs if certain signal conditions (trigger, time window, repetitions, etc.) are fulfilled. Thus many unwanted and unneeded signal data will not be stored.



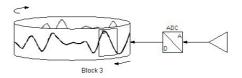
The digitalized signal will be stored to the onboard memory which acts as a ring buffer.



As soon as the trigger is released, a block of samples will be read from the ring buffer and will be saved to the hard disk.



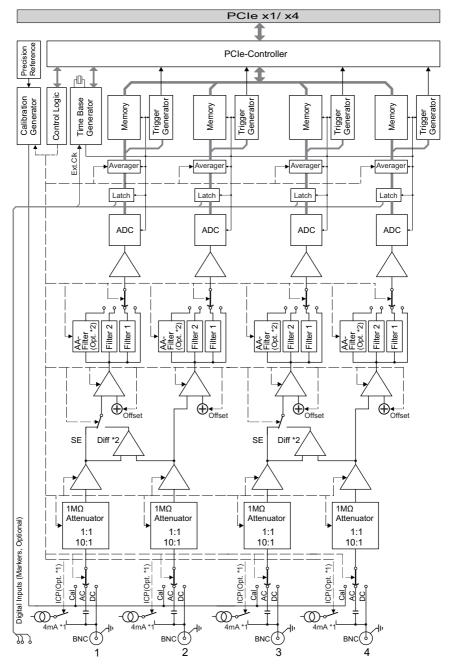
If a new trigger event within the actual block occurs, a new overlapping block will be saved.



If the ring buffer is full, the oldest measurement data will be overwritten with new incoming data. Usually, the overwritten data would be transferred to the hard disk before this happens. If too many events occur in a period of time, the ring buffer may overflow.

#### ECR Dual Mode

An other feature of ECR is the "Dual Mode". It allows to store a continuous measurement at a slower sampling rate than the captured blocks. For example fast transient can be captured at 10 MS/s by the triggered blocks while storing slower signals at 100 kHz over a long period of time.



#### 1.5 TPCE & TPCE-LE Block Diagram

#### 1.6 Standard Filter

On each channel a Low-Pass First Order Filter with 100 kHz or 1 MHz bandwidth can be activated. The analog bandwidth of the amplifier itself is set around the half of the maximum sampling rate, eg. 10 MHz for a 20 MHz board.

When the cards are used below the maximum sampling rate an internal digital filtering is done (Averaging of the oversampled signal). Therefor an Anti-Aliasing Filter is not needed in the most situations. The picture above shows a 20 MHz card used at 1 MHz. High frequency noise above 10 MHz is filtered by the analog bandwidth of the amplifier with 20 dB/dec. Noise between 500 kHz and 10 MHz is digital filtered with signal averaging.

#### 1.7 Trigger Logic

Elsys DAQ cards are available with two different trigger packages, the standard trigger package and the Advance Trigger package:

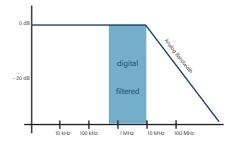
#### Standard Trigger

- Positive/Negative Slope
- Window In/Out

#### Advanced Trigger Package

- all Standard Trigger
- Pulse > & Pulse <</li>
- Delay > & Delay <</li>
- Slew Rate Trigger
- State Trigger
- AND Trigger linking
- Trigger on multiplied signals
   (Power Trigger)
- Trigger on Marker Inputs

Each channels can be the trigger source at once. The first channel which detects a trigger will trigger the measurement. One external Slope trigger is available on the 25-Pol D-SUB connector



# **1.8 Anti-Aliasing Filter Module** Anti-Aliasing Filters are an option and must be

installed at fabrication time.

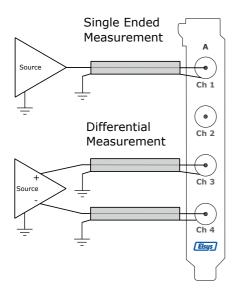
#### (TPCE Option AAF-4 or AAF-8).

				Stop band Attenua-	Passband Ripple	Additional Gain	and Offset
Cut-off (-3 dB) f <sub>o</sub>	f0 Tol. [±%]	Filter Type	Order	tion @ f > 4*fo	(max.) @ f < 0.6*fo	Error [±%]	Drift [ppm/°C]
200 Hz	5	Butterw.	6	> 54 dB	± 0.2 dB	0.1	50
300 Hz	5	Butterw	6	> 54 dB	± 0.2 dB	0.1	50
500 Hz	5	Butterw	6	> 54 dB	± 0.2 dB	0.1	50
700 Hz	5	Butterw	6	> 54 dB	± 0.2 dB	0.1	50
1 kHz	5	Butterw	6	> 54 dB	± 0.2 dB	0.1	50
1.5 kHz	5	Butterw	6	> 54 dB	± 0.2 dB	0.1	50
2 kHz	5	Butterw	6	> 54 dB	± 0.2 dB	0.1	50
3 kHz	5	Butterw	6	> 54 dB	± 0.2 dB	0.1	50
5 kHz	5	Butterw	6	> 54 dB	± 0.2 dB	0.1	50
7 kHz	5	Butterw	6	> 54 dB	± 0.2 dB	0.1	50
10 kHz	5	Butterw	6	> 54 dB	± 0.2 dB	0.1	50
15 kHz	5	Butterw	6	> 54 dB	± 0.2 dB	0.1	50
20 kHz	5	Butterw	6	> 54 dB	± 0.2 dB	0.1	50
30 kHz	5	Butterw	6	> 54 dB	± 0.2 dB	0.1	50
50 kHz	5	Butterw	6	> 54 dB	± 0.3 dB	0.1	50
70 kHz	10	Butterw	6	> 54 dB	± 0.4 dB	0.1	50
100 kHz	10	Butterw	6	> 54 dB	± 0.5 dB	0.1	50
200 kHz	10	Butterw	6	> 54 dB	± 0.5 dB	0.1	50
500 kHz	20	Elliptic	5	> 48 dB	± 0.5 dB	0.3	200
1 MHz	20	Elliptic	5	> 42 dB	± 0.5 dB	0.3	200
2 MHz	10	Butterw	4	> 42 dB	± 0.5 dB	0.2	100
5 MHz	10	Butterw	4	> 42 dB	± 0.5 dB	0.2	100

## 2. Input and Outputs

#### 2.1 Analog Inputs

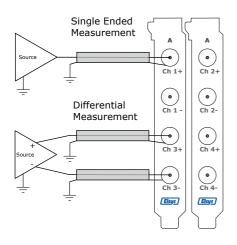
Single Ended Boards (SE)



Single Ended boards have one BNC connector per channel where the outside shielding is connected to chassis/protective Ground.

Two neighboring channel can be configured per software as differential input stage. In this case the signal must be connected as shown aside.

Differential Boards (DIFF)



Differential boards have two BNC connector per channel where the outside shielding is connected to chassis/protective Ground.

Single ended measurement can be performed by just using the + input of the BNC pair.

#### Input Ranges

The input range can be set individually for each channel. Different areas are available depending on the board type.

0% Offset	50% Offset	100% Offset	TPCE	TPCE-LE
0 - 100 mV	± 50 mV	-100 - 0 mV	~	×
0 - 200 mV	± 100 mV	-200 - 0 mV	~	~
0 - 500 mV	± 250 mV	-500 - 0 mV	✓	✓
0 - 1 V	± 500 mV	-1 - 0 V	~	~
0 - 2 V	±1V	-2 - 0 V	√	✓
0 - 5 V	± 2.5 V	-5 - 0 V	$\checkmark$	$\checkmark$
0 - 10 V	± 5 V	-10 - 0 V	√	✓
0 - 20 V	± 10 V	-20 - 0 V	$\checkmark$	$\checkmark$
0 - 50 V	± 25 V	-50 - 0 V	$\checkmark$	$\checkmark$
0 - 70 V	± 50 V	-70 - 0 V	~	×

Offset setting can be changed per channel in 1% steps from 0% to 100%.



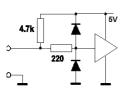
#### Attention

- Max. Input Voltage ± 100 VDC
- $7 V_{rms}$  with 50  $\Omega$  input switched on.

#### 2.2 Digital In/Out and Markers

#### Pin Out

Function	Description	Pin #	Input / Output
Trigger Out	TTL Pulse when device has triggered	1	Output
Armed Sync Clock Out	High when device is ready for trigger / Synchronization Clock Output (Configured in TranAX)	14	Output
!Disarm	Deactivate any trigger when low	15	Input
Start Recording	Start Recording at negative slope	3	Input
Trigger In	TLL Trigger input Note: There is no hysteresis. Therefore the trigger signal must have a minimum slew rate of 4 V/us. Otherwise, the triggering can take place on the wrong edge.	16	Input
Timebase In / PPS	External Timebase input or GPS PPS Input	4	Input
+5V	Power Output (max 500 mA)	17	Power Output
GND	Chassis Ground	5	
Marker A1	Digital Inputs Board A	18	Input
Marker A2	TTL Level (with internal Pull-Up)	6	Input
Marker A3		19	Input
Marker A4		7	Input
Marker A5		20	Input
Marker A6		8	Input
Marker A7		21	Input
Marker A8		9	Input
Marker B1	Digital Inputs Board B	22	Input
Marker B2	TTL Level (with internal Pull-Up)	10	Input
Marker B3		23	Input
Marker B4		11	Input
Marker B5		24	Input
Marker B6		12	Input
Marker B7		25	Input
Marker B8		13	Input



All digital inputs are pulled up to 5 V. Input Protection is  $\pm$  10 V for all inputs and outputs. Digital Marker inputs are captured synchronous with the ADC clock and are available when 14 bit resolution is used. In 16 bit mode, additional memory bits are needed and therefor no Marker are available.

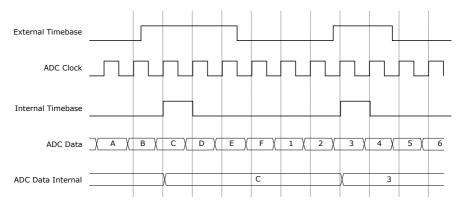
Sync Link

O Digital IO

**Elsys** 

#### **External Timebase**

The External Timebase can be used for capturing the measurement data at a specific moment. The external timebase is not a reference clock but will be synchronized to the internal ADC sampling clock. Therefor the external timebase must be at least two time slower than the ADC clock.



## 3. Specification

#### 3.1 Power Consumption

Power Rail	4 Channel		8 Channel		4 Channel 120 & 240 MHz	
	Тур.	Max.	Тур.	Max.	Тур.	Max.
+ 3.3 V	-	-	-	-	-	-
+5 V	-	-	-	-	-	-
+ 12 V	1.3 A	2.0 A	2.2 A	3.3 A	1.4 A	2.2 A
- 12V	-	-	-	-	-	-
Total Power	15.6 W	24 W	26.4 W	39.6 W	16.8 W	26.4 W

#### 3.2 Operating Conditions

- 0 45° C, 0 60° width active air circulation
- Max. Operating Altitude: 2000m

#### 3.3 Mechanical Specification

#### TPCE

- 4 Lane PCle Bus (x4)
- Size approx. 185x105 mm.
- 8-channel boards need 2 slots.
- With differential modules the number of required slots has to be doubled.

#### TPCE-LE

- 1 Lane PCIe Bus (x1)
- Size approx. 185x105 mm.
- 8-channel boards need 2 slots.
- With differential modules the number of required slots has to be doubled.

## 3.4 TPCE Specification

Module Type	TPCE-24016-4	TPCE-12016-4	TPCE-8016-4/8	TPCE-4016-4/8	
Number of Input Channels SE Module	4 single ended software s		4-Channel Modules: 4 single ended or 2 differential 8-Channel Modules: 8 single ended or 4 differential		
Number of Input Channels DIF Module	4 single ended software s		4-Channel Modules: 4 single ended or 4 differential 8-Channel Modules: 8 single ended or 8 differential		
Max. Sample Rate (all channels are sampled simultaneously)	240 MHz	120 MHz	80 MHz	40 MHz	
Amplitude Resolution	16 Bit up to 60 MHz 14 Bit up to 240 MHz	16 Bit up to 60 MHz 14 Bit up to 120 MHz	16 Bit up to 20 MHz 14 Bit up to 80 MHz	16 Bit up to 10 MHz 14 Bit up to 40 MHz	
Memory 4 Channel Module		Standard: 4 x 32 MW Optional: 4 x 128 M	/ords (= 256 MByte)  Words (= 1 GByte)		
Memory 8 Channel Module				Vords (= 256 MByte) 1Words (= 1 GByte)	
Input Amplifier					
Measurement Ranges	±50 mV – ±	50 V rsp. 0.1 V – 100 V (1	100 V limited to 70 V) ir	n 1, 2, 5 Steps	
Offset		0 - 100 % in steps of 0	.1% (Resolution 0.01 %)		
Input Impedance	1 MΩ (± 0.2 %) o // 26 pF		1 MΩ (± 0.2 %)	// 35 pF (± 5 %)	
Coupling	AC / DC so	ftware switchable (AC:	-3 dB at < 5 Hz), Inpu		
Bandwidth at Range ≥ 1 V	120 MHz	60 MHz	30 MHz	18 MHz	
Bandwidth at Range < 1 V	80 MHz	50 MHz	8 MHz	7 MHz	
Slew Rate (10 – 90 %) @ Range ≥ 1 V	4 ns	6 ns	13 ns	25 ns	
Slew Rate (10 – 90 %) @ Range < 1 V	6 ns	9 ns	50 ns	60 ns	
Settling Time to 1%	< 200 ns	< 200 ns	< 200ns	< 200 ns	
Low Pass Filter (RC-Filter)	2	Steps (1 MHz and 100	kHz) software switchab	le	
Antialiasing-Filter (optional)	200 Hz	z – 5 MHz, min. 4. order	Butterworth, software	setable	
Common Mode Range	Dif	ferential-Mode: ±8 V o	r +/-80 V at ranges. >	5 V	
Common Mode Rejection		(DC - 1 kHz); > 60 dB (	0		
Range Error (±)	max. 0.1 % (after auto	typ. 0.07 %	max. 0.1 %	typ. 0.03 % ocalibration)	
Offset Error (±)	max. 0.1 % (after autor	typ. 0.07 %	max. 0.1 %	typ. 0.02 % calibration)	
Offset Drift (±)		00 % + 0.1 mV) per °C, (will be compensate	typ. (0.0050 % + 0.03 r		
Input Noise: @ max. Sample Rate @ 5 MHz Sample Rate @ 10 HHz Sample Rate @ 10 kHz Sample Rate @ 10 kHz Sample Rate	< 0.250 mVrms < 0.120 mVrms < 0.070 mVrms < 0.040 mVrms < 0.025 mVrms	< 0.200 mVrms < 0.120 mVrms < 0.070 mVrms < 0.040 mVrms < 0.025 mVrms	< 0.200 mVrms < 0.120 mVrms < 0.070 mVrms < 0.040 mVrms < 0.020 mVrms	< 0.180 mVrms < 0.110 mVrms < 0.060 mVrms < 0.040 mVrms < 0.015 mVrms	*2
© 10 Noise Ratio SNR: @ max. Sample Rate @ 10 MHz Sample Rate @ 5 MHz Sample Rate @ 10 MHz Sample Rate @ 100 KHz Sample Rate @ 10 KHz Sample Rate	58 dB 70 dB 72 dB 77 dB 81 dB 84 dB	60 dB 70 dB 72 dB 77 dB 81 dB 84 dB	59 dB 62 dB 66 dB 69 dB 79 dB 89 dB	62 dB 68 dB 70 dB 74 dB 82 dB 90 dB	*3
Channel Isolation (Crosstalk) @ 10 kHz	> 74	dB		0 dB 0 dB	
Ranges < 1V Special : Autocalibration	Auto adjustment of	gain and offset in all m			
Trigger	4 may 1 11		a Falsa with any W	4 h	
Number of Trigger Channels		o analog inputs, pos./ne Window IN, V	Window OUT	-	
Advanced Trigger (Option)	On all analog inputs: Slew Rate, Pulse Width, Pulse Pause or Period (too short or too long = Missing Event), State (above / below), AND link, Product (trigger signal is calculated from 2 channels)				
External Trigger input		1 per System (TTL),	, pos. or neg. Edge		
Trigger Delay	-100	% (Pretrigger) to +200		steps	
Miscellaneous					
	8 (2 per analog channel) (TTL)				
Digital Inputs (Marker)	Optoco			l option	
Digital Inputs (Marker)		upler Connection Box (	5 to 48 V) as additiona		
	Trigger, Arm/Disarm, E		5 to 48 V) as additiona 10 MHz), external comn	nand to start recording	

Module Type	TPCE-2016-4/8	TPCE-1016-4/8	TPCE-0516-4/8	TPCE-0216-4/8			
Number of Input Channels SE Module		<ul> <li>4-Channel Modules: 4 single ended or 2 differential</li> <li>8-Channel Modules: 8 single ended or 4 differential</li> </ul>					
Number of Input Channels DIF Module		Channel Modules: 4 sin Channel Modules: 8 sin					
Max. Sample Rate (all channels are sampled simultaneously)	20 MHz	10 MHz	5 MHz	2 MHz			
Amplitude Resolution	16 Bit up to 5 MHz 14 Bit up to 20 MHz	16 Bit up to 5 MHz 14 Bit up to 10 MHz	16 Bit up to 5 MHz	16 Bit up to 2 MHz			
Memory 4 Channel Module		Standard: 4 x 32 MW Optional: 4 x 128 M					
Memory 8 Channel Module		Standard: 8 x 16 MW Optional: 8 x 64 M					
Input Amplifier							
Measurement Ranges	±50 mV – ±	50 V rsp. 0.1 V – 100 V (1		1, 2, 5 Steps			
Offset		0 - 100 % in steps of 0	.1% (Resolution 0.01 %)				
Input Impedance		1 MΩ (± 0.2 %) /	// 35 pF (± 5 %)				
Coupling	AC / DC so	ftware switchable (AC:	-3 dB at < 5 Hz), Inpu	ts invertible			
Bandwidth at Range ≥ 1 V	10 MHz	5 MHz	2.5 MHz	1 MHz			
Bandwidth at Range < 1 V	6 MHz	4 MHz	2.5 MHz	1 MHz			
Slew Rate (10 – 90 %) @ Range ≥ 1 V	40 ns	70 ns	80 ns	180 ns			
Slew Rate (10 – 90 %) @ Range < 1 V	70 ns	80 ns	80 ns	180 ns			
Settling Time to 1%	< 200ns	< 200 ns	< 300 ns	< 500 ns			
Low Pass Filter (RC-Filter)	2	Steps (1 MHz and 100 k	kHz) software switchab	le			
Antialiasing-Filter (optional)	200 Hz	z – 5 MHz, min. 4. order	Butterworth, software s	etable			
Common Mode Range	Dif	ferential-Mode: ±8 V o	r +/-80 V at ranges. > 5	δV			
Common Mode Rejection	> 74 dB (DC - 1 kHz); > 60 dB ( - 100 kHz); > 40 dB ( - 20 MHz)						
Range Error (±)	max. 0.1 % typ. 0.03 % (after autocalibration)						
Offset Error (±)		max. 0.1 % (after autor	typ. 0.03 % alibration)				
Offset Drift (±)	max. (0.01	00 % + 0.1 mV) per °C, (will be compensated		nV) per °C			
Input Noise: @ max. Sample Rate @ 5 MHz Sample Rate @ 1 MHz Sample Rate @ 100 kHz Sample Rate @ 10 kHz Sample Rate	< 0.080 mVrms < 0.060 mVrms < 0.030 mVrms < 0.020 mVrms < 0.010 mVrms	< 0.080 mVrms < 0.060 mVrms < 0.030 mVrms < 0.020 mVrms < 0.010 mVrms	< 0.060 mVrms < 0.060 mVrms < 0.030 mVrms < 0.020 mVrms < 0.010 mVrms	< 0.060 mVrms < 0.020 mVrms < 0.020 mVrms < 0.010 mVrms	*2		
@ 10 kHz Sample Rate     Signal to Noise Ratio SNR:     @ max. Sample Rate     @ 10 MHz Sample Rate     @ 1 MHz Sample Rate     @ 10 kHz Sample Rate     @ 100 kHz Sample Rate	67 dB 70 dB 72 dB 79 dB 84 dB	70 dB 70 dB 72 dB 79 dB 84 dB	72dB - 72 dB 79 dB 84 dB	72 dB - - 79 dB 84 dB	*3 *4		
@ 10 kHz Sample Rate	90 dB	90 dB	90 dB	90 dB			
Channel Isolation (Crosstalk) @ 10 kHz Ranges < 1V		> 80 > 60					
Special : Autocalibration Trigger	Auto adjustment of	gain and offset in all m	easurement ranges. (In	itiated by software)			
Number of Trigger Channels	4 or 8, coupled	d to analog inputs, pos./ Window IN, V		out hysteresis,			
Advanced Trigger (Option)		Slew Rate, Pulse Width, e (above / below), AND 2 char	link, Product (trigger si				
External Trigger input		1 per System (TTL),					
Trigger Delay	100	% (Pretrigger) to +200		tons			
Miscellaneous	-100	in reingger) to +200	/o (i Ostingger) iil 1 % s	icpo			
Digital Inputs (Marker)	Ontoco	8 rsp. 16 (2 per anal oupler Connection Box (		ontion			
Ext. Control Inputs (TTL))		Ext. Sampling (fmax = ) to start re	4 of the max sample rat				
Status Outputs (TTL)	т	rigger Output, Armed (	-	)			
ICP <sup>*</sup> Sensor Supply (Option)		ImA Integrated Current					
isi sensor supply (Option)	4		. 5.761 101 piezo serisor:				

\*1) At 16 bit modules, the resolution will be reduced to 14 bits at sample rates over 1/4 of the max. sample rate.

\*2)

The input noise depends on the sample rate. At 14 bit modules the SNR will be reduced by 2 dB \*3)

\*4) At 8-channel modules the SNR will be reduced by 3 dB

## 3.5 TPCE-LE Specification

Module Type	TPCE-LE-24014-4	TPCE-LE-12014-4	TPCE-LE-8014-4/8	TPCE-LE-4014-4/8	
Number of Input Channels SE Module		4 single ended or 2 differential software switchable		gle ended or 2 differential gle ended or 4 differential	
Number of Input Channels DIF Module	4 single ended software s	or 4 differential witchable	4-Channel Modules: 4 single ended or 4 differential 8-Channel Modules: 8 single ended or 8 differential		
Max. Sample Rate (all channels are sampled simultaneously)	240 MHz	120 MHz	80 MHz	40 MHz	
Amplitude Resolution	14 Bit up to 240 MHz (16 Bit up to 60 MHz optional)	14 Bit up to 120 MHz (16 Bit up to 60 MHz optional)	14 Bit up to 80 MHz (16 Bit up to 20 MHz optional)	14 Bit up to 40 MHz (16 Bit up to 10 MHz optional)	
Memory 4 Channel Module			Vords (= 256 MByte) 1Words (= 1 GByte)		
Memory 8 Channel Module	Standard: 8 x 16 MWords (= 256 MByte) Optional: 8 x 64 MWords (= 1 GByte)				
Input Amplifier					
Measurement Ranges	±	:100 mV - ±25 V rsp. 0.	2 V – 50 V in 1, 2, 5 Step	IS	
Offset			0.1% (Resolution 0.01 %)		
Input Impedance	1 MΩ (± 0.2 %) c // 26 pF		1 MΩ (± 0.2 %)	// 35 pF (± 5 %)	
Coupling	AC / DC so	ftware switchable (AC:	-3 dB at < 5 Hz), Inpu	ts invertible	
Bandwidth at Range ≥ 1 V	120 MHz	60 MHz	30 MHz	18 MHz	
Bandwidth at Range < 1 V	80 MHz	50 MHz	8 MHz	7 MHz	
Slew Rate (10 – 90 %) @ Range $\geq$ 1 V	4 ns	6 ns	13 ns	25 ns	
Slew Rate (10 – 90 %) @ Range < 1 V	6 ns	9 ns	50 ns	60 ns	
Settling Time to 1%	< 200 ns	< 200 ns	< 200ns	< 200 ns	
Low Pass Filter (RC-Filter)	2	Steps (1 MHz and 100	kHz) software switchab	le	
Antialiasing-Filter (optional)			Butterworth, software s		
Common Mode Range			or +/-80 V at ranges. >		
Common Mode Rejection	> 60 dB (DC – 1 kHz); > 54 dB ( – 100 kHz); > 40 dB ( – 20 MHz)				
Range Error (±)	max. 0.1 % typ. 0.07 % max. 0.1 % typ. 0.03 % (after autocalibration) (after autocalibration)				
Offset Error (±)	(after autor	max. 0.1 % typ. 0.07 % max. 0.1 % typ. 0.02 % (after autocalibration) (after autocalibration)			
Offset Drift (±)	max. (0.01		typ. (0.0050 % + 0.03 n d by autocalibration)	ν) per °C	
Input Noise: @ max. Sample Rate @ 5 MHz Sample Rate @ 10 MHz Sample Rate @ 100 kHz Sample Rate @ 10 kHz Sample Rate	< 0.250 mVrms < 0.120 mVrms < 0.070 mVrms < 0.040 mVrms < 0.025 mVrms	< 0.200 mVrms < 0.120 mVrms < 0.070 mVrms < 0.040 mVrms < 0.025 mVrms	< 0.200 mVrms < 0.120 mVrms < 0.070 mVrms < 0.040 mVrms < 0.020 mVrms	< 0.180 mVrms < 0.110 mVrms < 0.060 mVrms < 0.040 mVrms < 0.015 mVrms	*2
Signal to Noise Ratio SNR: @ max. Sample Rate @ 10 MHz Sample Rate @ 5 MHz Sample Rate @ 10 MHz Sample Rate @ 100 kHz Sample Rate @ 10 kHz Sample Rate	58 dB 70 dB 72 dB 77 dB 81 dB 84 dB	60 dB 70 dB 72 dB 77 dB 81 dB 84 dB	59 dB 62 dB 66 dB 69 dB 79 dB 89 dB	62 dB 68 dB 70 dB 74 dB 82 dB 90 dB	*3
Channel Isolation (Crosstalk) @ 10 kHz	> 74	dB		0 dB	
Ranges < 1V				) dB	
Special : Autocalibration	Auto adjustment of	gain and offset in all m	neasurement ranges. (In	maled by software)	
Trigger Number of Trigger Channels	4 coupled to	o analog inputs, pos./n	eg.Edge, with or withou	t hysteresis,	
Number of mgger channels	On all analog inputs:		Window OUT	(too short or too long	
Advanced Trigger (Option)	On all analog inputs: Slew Rate, Pulse Width, Pulse Pause or Period (too short or too long = Missing Event), State (above / below), AND link, Product (trigger signal is calculated from 2 channels)				
External Trigger input		1 per System (TTL)	), pos. or neg. Edge		
Trigger Delay	-100		% (Posttrigger) in 1 % s	steps	
Miscellaneous					
Digital Inputs (Marker)	<b>.</b>		channel) (TTL)		
			(5 to 48 V) as additional		
Ext. Control Inputs (TTL))			10 MHz), external comm		
Status Outputs (TTL)			(=True during recording		
ICP <sup>®</sup> Sensor Supply (Option)	2	IMA Integrated Current	Power for piezo sensor	S	

Module Type	TPCE-LE-2014-4/8	TPCE-LE-1014-4/8	TPCE-LE-0514-4/8	TPCE-LE-0214-4/8		
Number of Input Channels SE Module		4-Channel Modules: 4 single ended or 2 differential 8-Channel Modules: 8 single ended or 4 differential				
Number of Input Channels DIF Module		4-Channel Modules: 4 single ended or 4 differential 8-Channel Modules: 8 single ended or 8 differential				
Max. Sample Rate (all channels are sampled simultaneously)	20 MHz	10 MHz	5 MHz	2 MHz		
Amplitude Resolution	14 Bit up to 20 MHz (16 Bit up to 5 MHz optiona)	14 Bit up to 10 MHz (16 Bit up to 5 MHz optional)	14 Bit (16 Bit Optional)	14 Bit (16 Bit Optional)		
Memory 4 Channel Module		Standard: 4 x 32 MW Optional: 4 x 128 M				
Memory 8 Channel Module		Standard: 8 x 16 MW Optional: 8 x 64 M				
Input Amplifier						
Measurement Ranges	±	100 mV - ±25 V rsp. 0.2		s		
Offset		0 - 100 % in steps of 0	, ,			
Input Impedance		1 MΩ (± 0.2 %) /				
Coupling		ftware switchable (AC:	<i></i>			
Bandwidth at Range ≥ 1 V	10 MHz	5 MHz	2.5 MHz	1 MHz		
Bandwidth at Range < 1 V	6 MHz 40 ns	4 MHz 70 ns	2.5 MHz 80 ns	1 MHz 180 ns		
Slew Rate (10 – 90 %) @ Range ≥ 1 V Slew Rate (10 – 90 %) @ Range < 1 V	40 hs 70 ns	80 ns	80 ns	180 ris		
Settling Time to 1%	< 200ns	< 200 ns	< 300 ns	< 500 ns		
Low Pass Filter (RC-Filter)		Steps (1 MHz and 100 l				
Antialiasing-Filter (optional)		z – 5 MHz, min. 4. order				
Common Mode Range		ferential-Mode: ±8 V o				
Common Mode Rejection			-			
	> 60 dB (DC – 1 kHz); > 54 dB ( – 100 kHz); > 40 dB ( – 1 MHz) max. 0.1 % typ. 0.03 %					
Range Error (±)		(after autoc	alibration)			
Offset Error (±)		max. 0.1 % (after autor	alibration)			
Offset Drift (±)	max. (0.01	00 % + 0.1 mV) per °C, (will be compensated		nV) per °C		
Input Noise: @ 5 MHz Sample Rate @ 10 MHz Sample Rate @ 100 kHz Sample Rate @ 10 kHz Sample Rate	< 0.080 mVrms < 0.060 mVrms < 0.030 mVrms < 0.020 mVrms < 0.010 mVrms	< 0.080 mVrms < 0.060 mVrms < 0.030 mVrms < 0.020 mVrms < 0.010 mVrms	< 0.060 mVrms < 0.060 mVrms < 0.030 mVrms < 0.020 mVrms < 0.010 mVrms	< 0.060 mVrms < 0.030 mVrms < 0.020 mVrms < 0.010 mVrms	*2	
Signal to Noise Ratio SNR: @ max. Sample Rate @ 10 MHz Sample Rate @ 1 MHz Sample Rate @ 100 kHz Sample Rate @ 100 kHz Sample Rate	67 dB 70 dB 72 dB 79 dB 84 dB 90 dB	70 dB 70 dB 72 dB 79 dB 84 dB 90 dB	72dB - 72 dB 79 dB 84 dB 90 dB	72 dB - - 79 dB 84 dB 90 dB	*3 *4	
Channel Isolation (Crosstalk) @ 10 kHz Ranges < 1V		> 80 > 60				
Special : Autocalibration	Auto adjustment of	gain and offset in all m		itiated by software)		
Trigger		-				
Number of Trigger Channels	4 or 8, coupled	d to analog inputs, pos./ Window IN, V		out hysteresis,		
Advanced Trigger (Option)		Slew Rate, Pulse Width, e (above / below), AND 2 char	link, Product (trigger si			
External Trigger input		1 per System (TTL),	,			
Trigger Delay	-100	% (Pretrigger) to +200		teps		
Miscellaneous						
Digital Inputs (Marker)	Optoco	8 rsp. 16 (2 per anal oupler Connection Box (		option		
Ext. Control Inputs (TTL))		Ext. Sampling (fmax = 1 to start re	4 of the max sample rat			
Status Outputs (TTL)	Т	rigger Output, Armed (	0	)		
ICP <sup>®</sup> Sensor Supply (Option)		ImA Integrated Current				
		0				

\*2)

\*3)

The input noise depends on the sample rate. At 14 bit modules the SNR will be reduced by 2 dB At 8-channel modules the SNR will be reduced by 3 dB \*4)

## 4. Synchronization

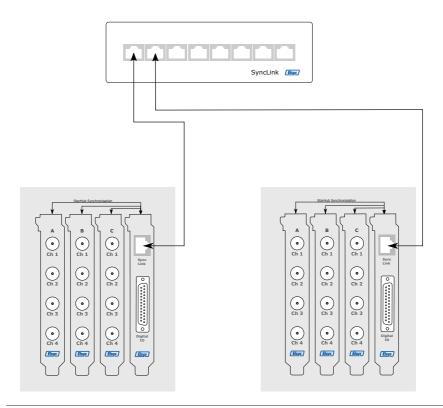
#### 4.1 StarHub

The StarHub synchronization board allows to synchronize up to 16 Boards inside of an instruments. The StarHub generates a master Clock and distributes any Trigger event from and to all connected boards. This way, every board in the system can be source and destination of any trigger event. The synchronization precision is one sample over all connected boards.

#### 4.2 SyncLink

The SyncLink is the next higher level of synchronization and allows to synchronize up to 8 instruments. The connection is made over standard Cat. 6 Ethernet cables up to 10 m length. When connected, the SyncLink act as master clock generator and distributes any trigger event from and to all devices. Any device can be the source of the trigger.

Note: No measurement data are transmitted over the Sync-Link connection. Therefor an Ethernet connection must be established in addition.



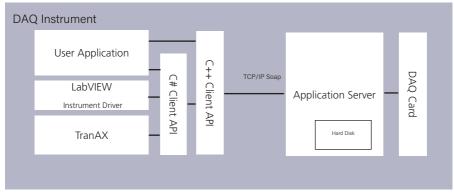
## 5. Software API

All DAQ cards as also the TraNET devices are based on the same Server-Client Software architecture. Any client application can access the data acquisition device over an IP address either locally or over a network. This way distributed measurement set-ups can be easily built-up.

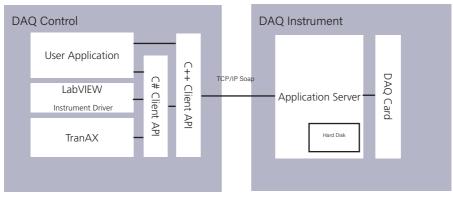
The lowest level accessible from a user application is a C++ interface. This interface handles all network communication between the Application and the Application Server. C# Applications can access a high level API for easy software integration. Several application can access the same device on the same time and get updated about any status change of the device automatically.

For more information visit: https://www.elsys-instruments.com/en/rdk-tpcaccess/

https://github.com/elsysdaq/tpcaccess



Control/DAQ Software runs on machine where the DAQ cards are installed



Control/DAQ Software runs on a different machine and controls multiple DAQ instruments.

#### 5.1 LabVIEW

Elsys provides a LabVIEW instrument driver which is fully compliant with the NI driver design guidelines.

The application server encapsulates all necessary task for controlling the different measurement modes described above, including data streaming to the hard drive. Therefor no challenging programming is needed for streaming application as this is already integrated into the Server software.



For more information visit:

https://www.elsys-instruments.com/en/labview/

EU Declaration of Conformity				
Declaration Number:	231014			
The Manufacturer:	Elsys AG Mellingerstrasse 12 5443 Niederrohrdorf Switzerland			
Declare that the product:	Data Acquisition Module TPCE   TPCE-LE   TPCE-GN			
	4 or 8 channel data acquisition modules with voltage and IEPE input channel type and 2 to 240 MS/s max sampling rate.			
is conformal to the followin	g directives and standards:			
Product Standards:	IEC 61326-1:2020 (ed.3.0) CISPR 11:2015 class B CISPR 11:2015/AMD1:2016 class B CISPR 11:2015/AMD2:2019 class B CISPR 32:2015 class B CISPR 32:2015/AMD1:2019 class B			
Basic Standards:	EN 61000-3-2:2019 IEC 61000-3-2:2018/AMD1:2020 EN 61000-3-3:2013 IEC 61000-3-3:2013 IEC 61000-3-3:2013/AMD1:2017 IEC 61000-4-2:2009 IEC 61000-4-2:2009 IEC 61000-4-3:2020 EN 61000-4-3:2020 EN 61000-4-3:2020 EN 61000-4-4:2012 IEC 61000-4-5:2014 IEC 61000-4-5:2014 IEC 61000-4-5:2014/AMD1:2017 IEC 61000-4-5:2014/AMD1:2017 EN 61000-4-6:2014IEC 61000-4-6:2013 (ed 4.0) EN 61000-4-8:2010 IEC 61000-4-8:2009 EN 61000-4-11:2020 IEC 61000-4-11:2020			
This declaration of conform manufacturer.	ity is issued under the exclusive responsibility of the			
Niederrohrdorf, 09.10.2023	D D C Elsys AG			

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#### File Revision:

Date	Description
29.01.2021	Manual Update
09.11.2023	Manual Update